



JVL ...when motors must be controlled



OCX-demo in Excel





Programming

- Give each motor an address with MacTalk (3 – 5)
- Start Excel and set it up with Visual Basic
- Design the screen
- Setup the communication - MacComm
- Put in the program text
- Design end
- Run makro
- Change value in "Set mode" and "Set position"
- Press "Start" and the chosen motor will change to Position mode and run the position
- Press "Start" again and actual position at the screen will update.
- Press "Stop" and the motor will change to Passive mode





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OCX -driver

RS232/485

MAC motor adress

3

**MAC00-
B1**

4

**MAC00-
B1**

5

**MAC00-
R1**

X

Y

Z

MacTalk

MacRegIO

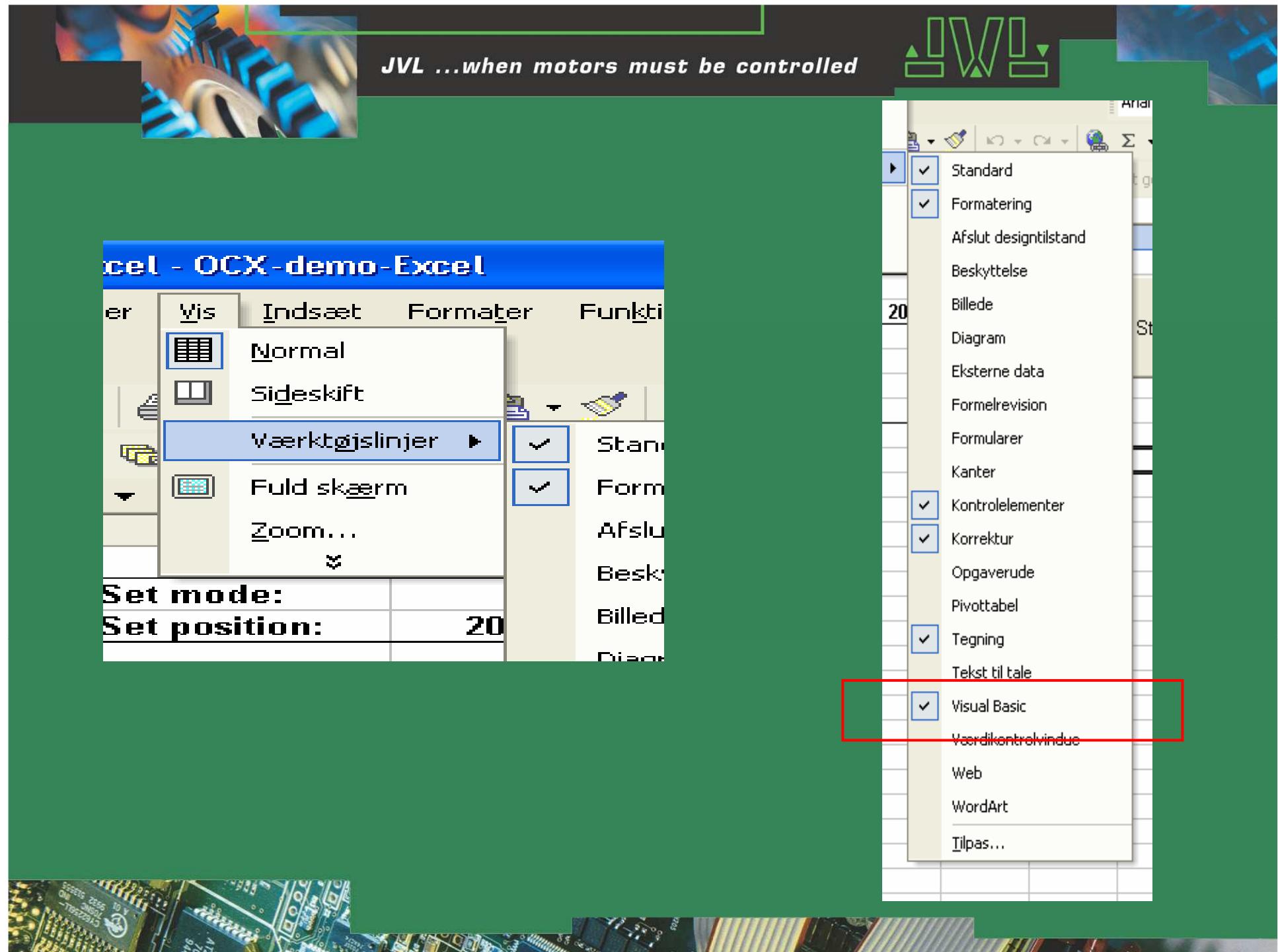
OCX

VB,
LabView,
....

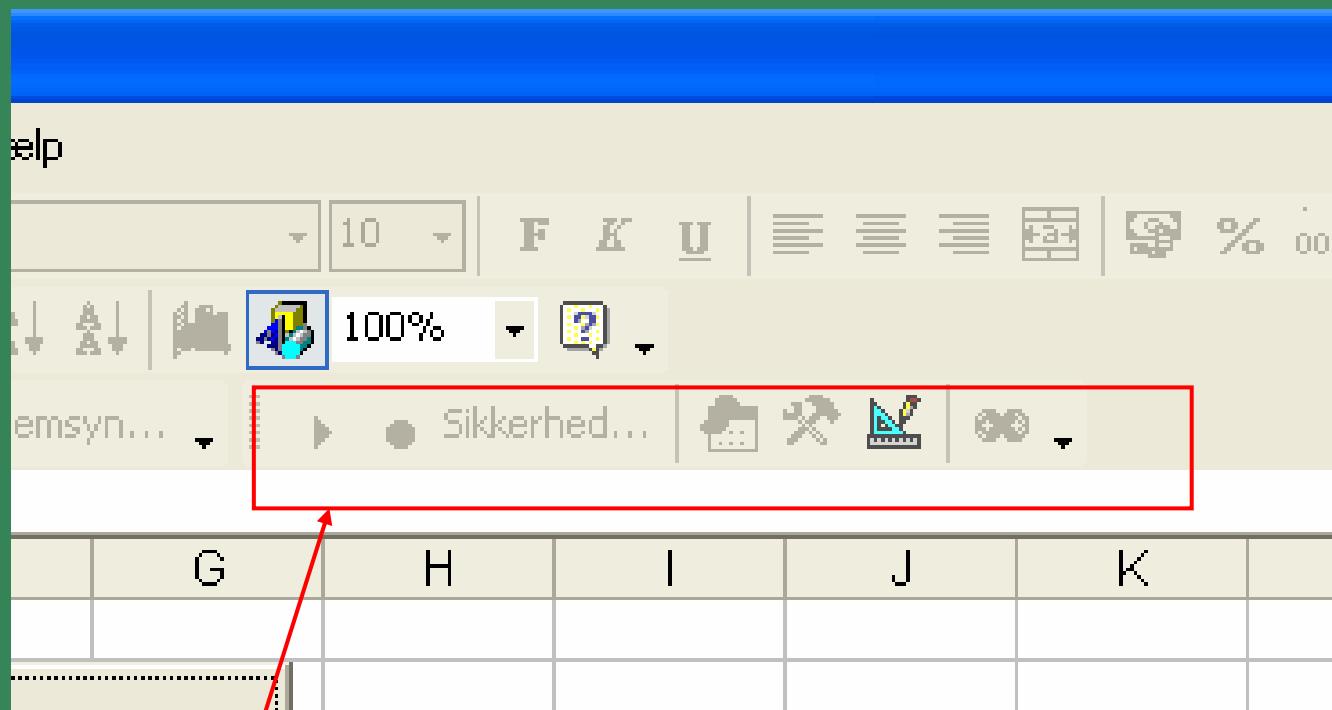
PC

OCX driver placed in
C:\WINDOWS\MacComm



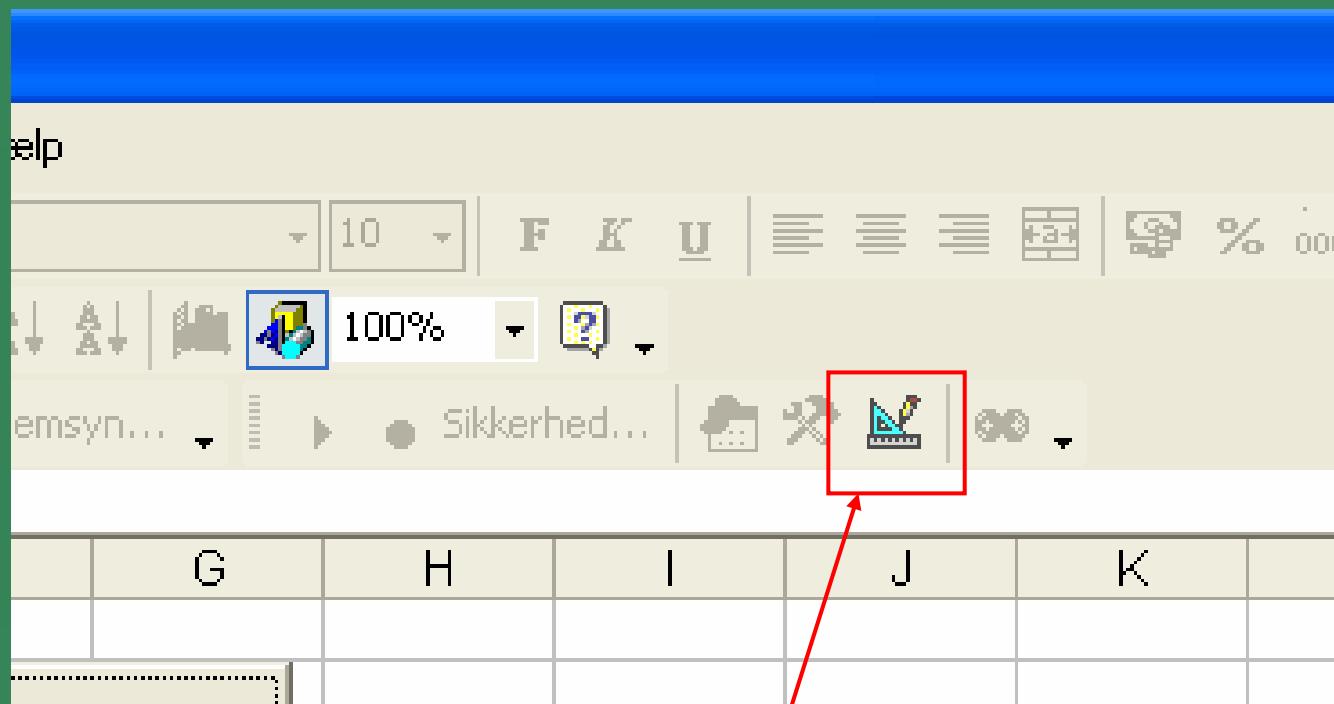


OCX-demo in Excel



Visual Basic commands in Excel

OCX-demo in Excel



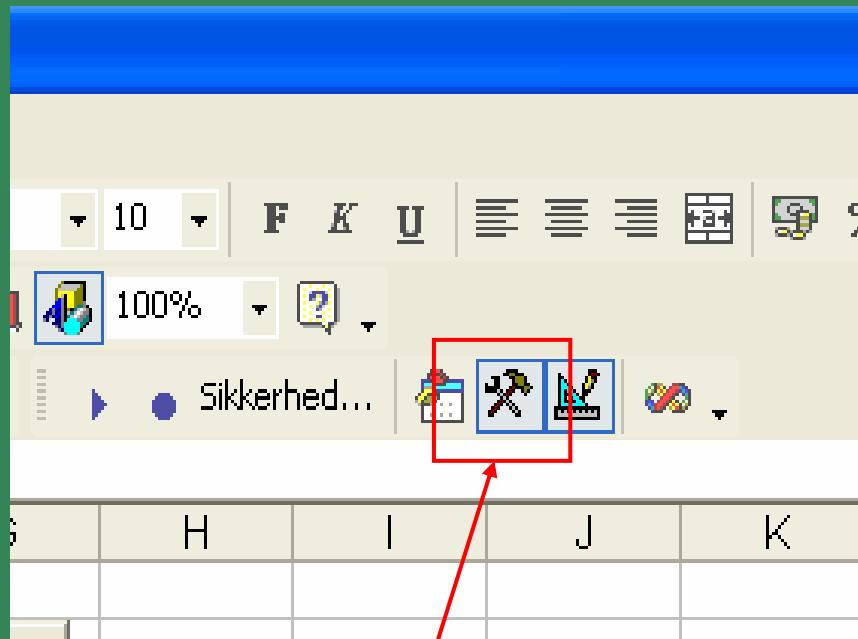
Design new application



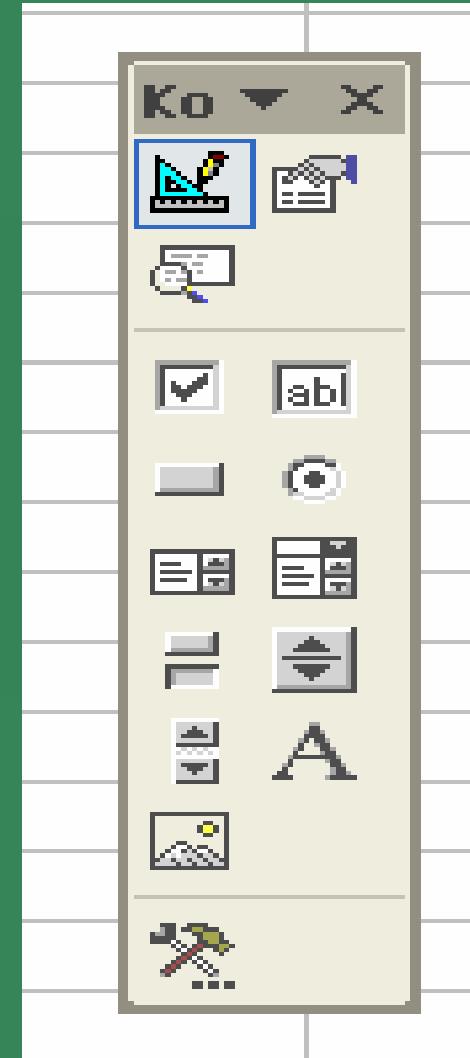
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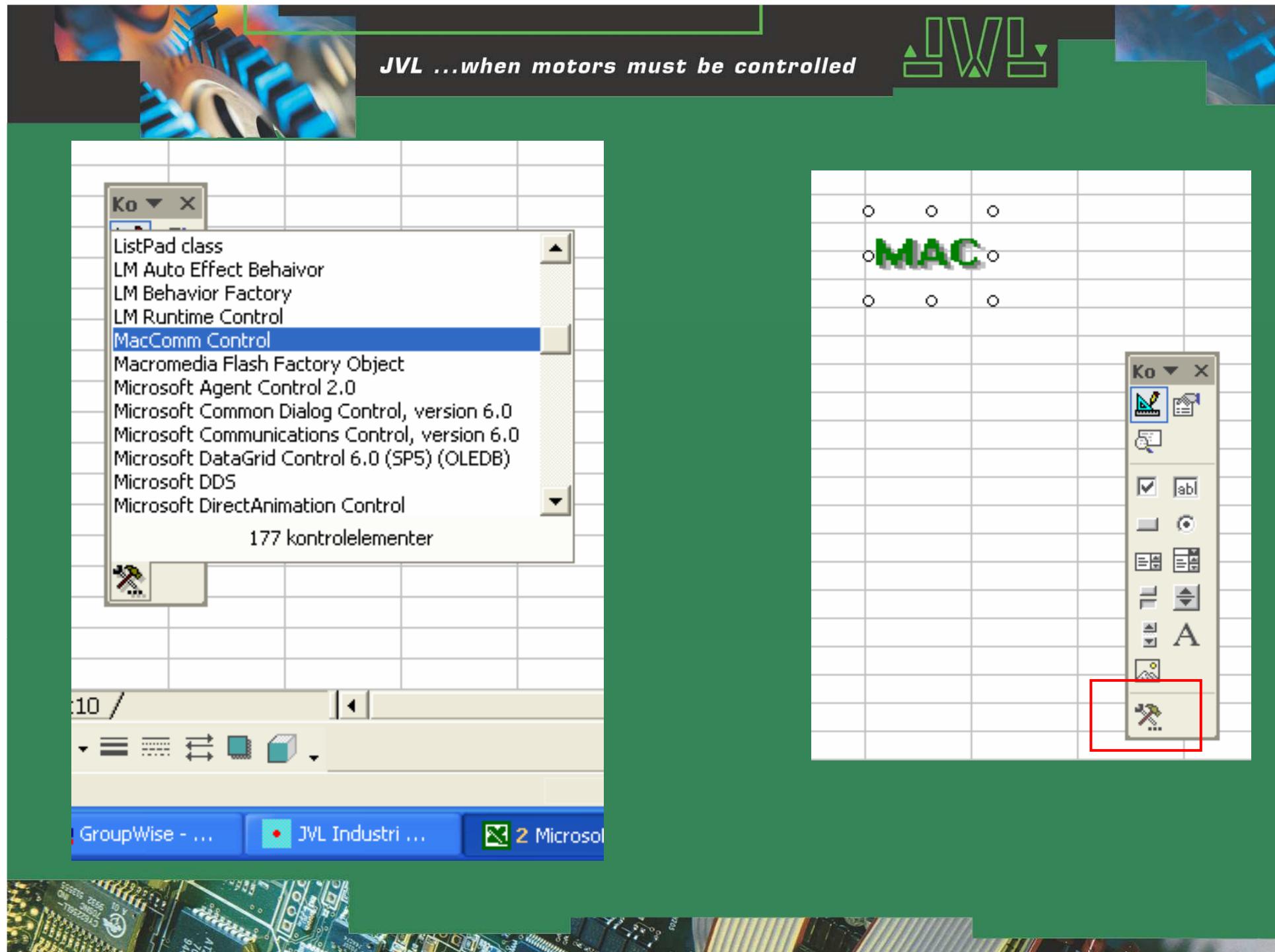


OCX-demo in Excel



Control elements





Properties

MacComm1 MacComm

Alphabetic Categorized

(About)

(Custom)

Name MacComm1

AutoLoad False

ComPort 2

Enabled True

Height 40,5

Left 224,25

Locked True

Placement 2

PrintObject True

Retries 5

Shadow False

Top 109,5

Visible False

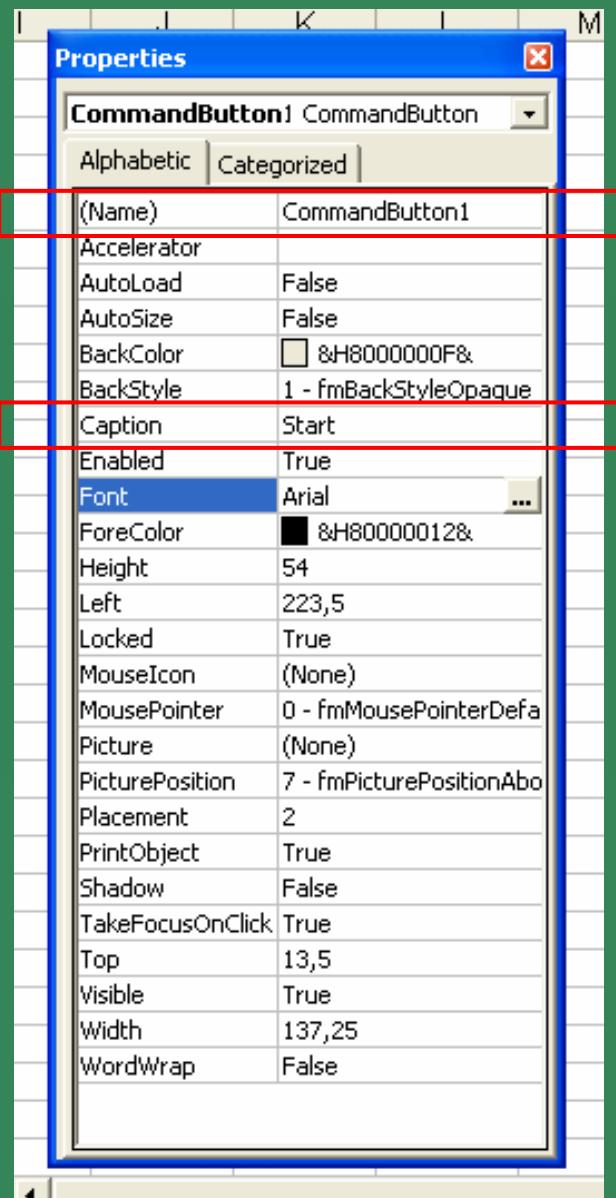
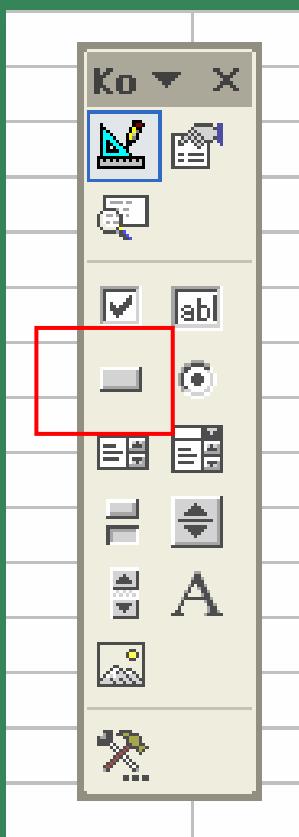
Width 56,25



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CommandButton





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	A	B	C	D
1				
2		Set mode:	0	
3		Set position:	20000	
4				
5				
6				
7		Result:	-1	
8				
9				

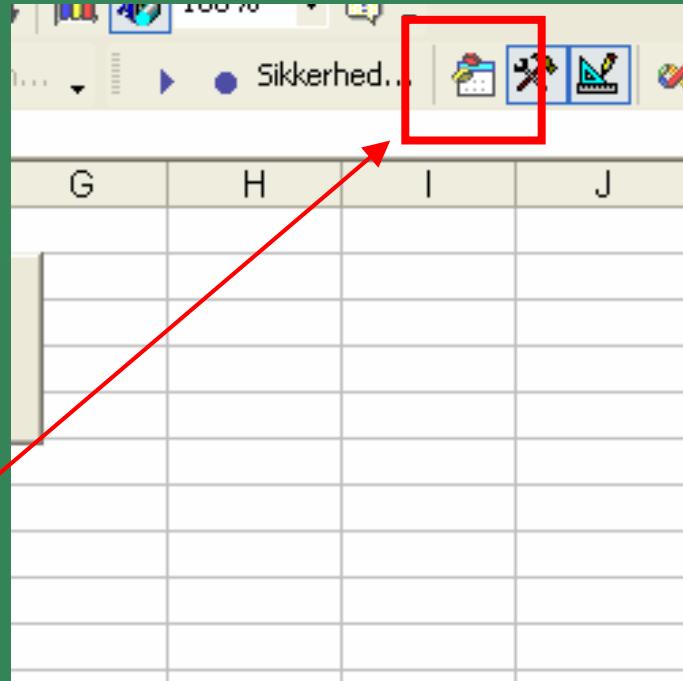
Design screen

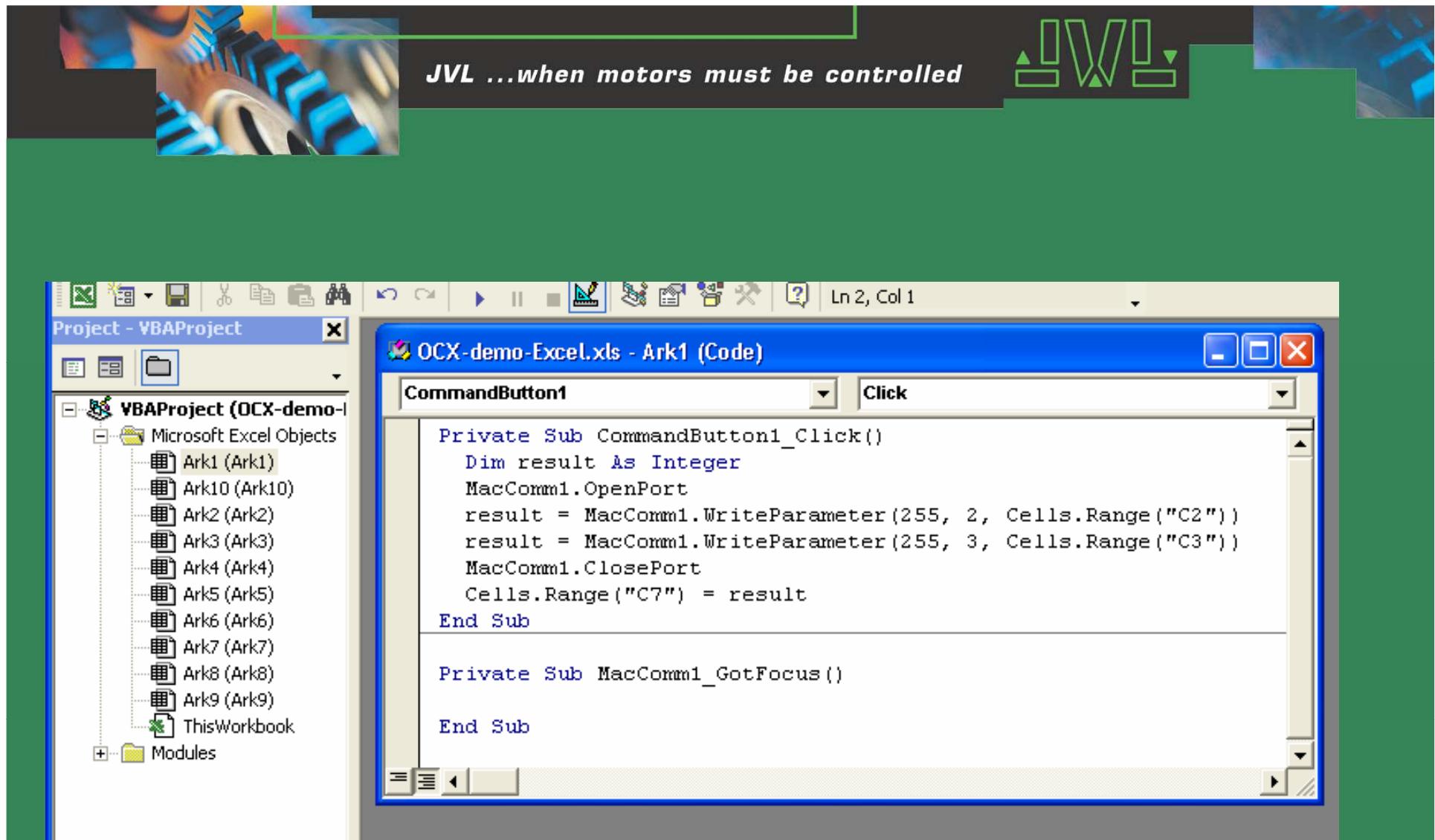


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JVL

Program
Text





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IVI

Project - VBAProject

OCX-demo-Excel.xls - Ark1 (Code)

CommandButton1 Click

```
Private Sub CommandButton1_Click()
    Dim result As Integer
    MacComm1.OpenPort
    result = MacComm1.WriteParameter(255, 2, Cells.Range("C2"))
    result = MacComm1.WriteParameter(255, 3, Cells.Range("C3"))
    MacComm1.ClosePort
    Cells.Range("C7") = result
End Sub

Private Sub MacComm1_GotFocus()
End Sub
```

Address 255 – Commands sent to all motors



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B	C	D	E	F	G
Set mode:	0				
Set position:	20000				
Result:	-1				

Start

MAC

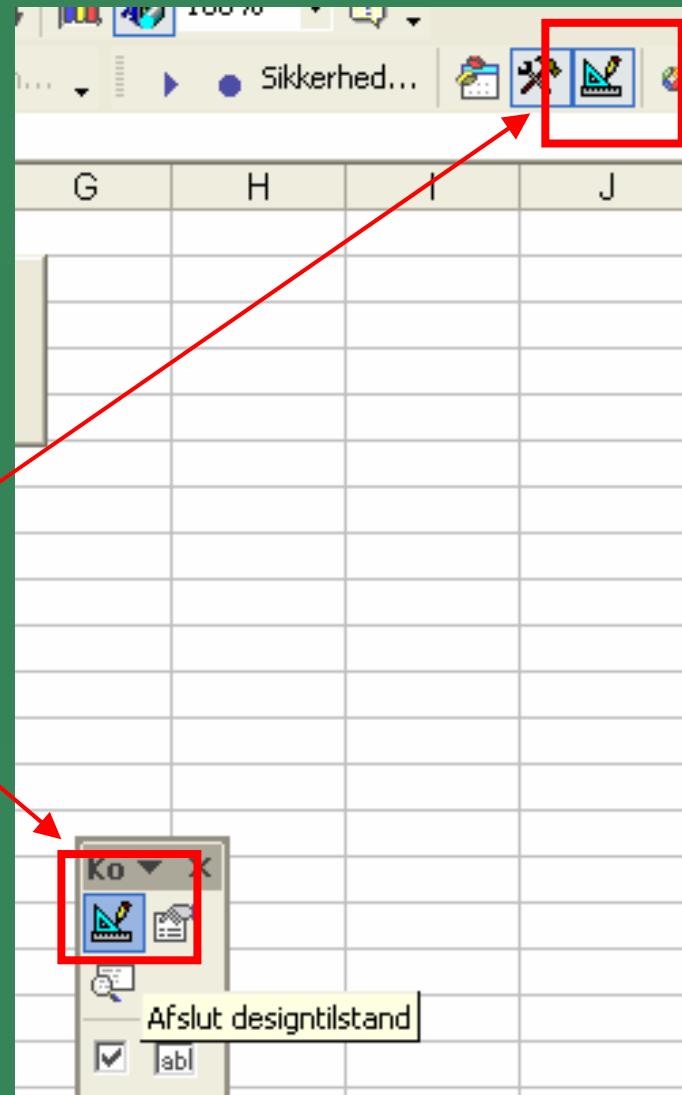




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W

Design end





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A	B	C	D	E	F	G
		Set mode: 2				
		Set position: 123				
		Result: -1				

Set mode and position and press "Start"

